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6 A Soil Moisture Data Assimilation System for	
7 Pakistan using PODEn4DVar and the Communi	ity
8 Land Model Version 4.5	
9 Taria MAHMOOD ^{1,2,3} Zhenghui XIE ^{1,2} * Binghao HA ¹ Ammara HABIB ^{1,2} and Pashid	
10 MAHMOOD ⁴	
11 1 State Key Laboratory of Numerical Modeling for Atmospheric Sciences and Geophysi	cal
12 Fluid Dynamics (LASG), Institute of Atmospheric Physics, Chinese Academy of Science	<i>es</i> ,
13 Beijing 100029, China	
14 2 University of Chinese Academy of Sciences, Beijing 100049, China	
15 3 Pakistan Meteorological Department, Islamabad, Pakistan	
16 4 Key Laboratory of Water Cycle and Related Land Surface Processes, Institute of Geographi	с
17 Science and Natural Resources Research, Chinese Academy of Sciences, Beijing 100101, Chin	a
18	
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²⁵ * Corresponding author: <u>zxie@lasg.iap.ac.cn</u> .	
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29 30

ABSTRACT

31 Soil moisture is an important state variable for land-atmosphere interactions. It is a 32 vital land surface variable for research on hydrology, agriculture, climate, and drought monitoring. In current study, a soil moisture data assimilation framework has been 33 34 developed using the Community Land Model version 4.5 and the PODEn4DVar 35 algorithm. Assimilation experiments were conducted at four agricultural sites in Pakistan 36 by assimilating *in-situ* soil moisture observations. The results showed that it was a reliable system. To quantify further the feasibility of the data assimilation (DA) system, 37 38 soil moisture observations from the top four soil-depths (0-5 cm, 5-10 cm, 10-20 cm, 39 and 20–30 cm) were assimilated. The evaluation results indicated that the DA system 40 improved soil moisture estimation. In addition, updating the soil moisture in the upper soil layers of CLM4.5 could improve soil moisture estimation in deeper soil layers (layer 41 42 7, L7~62.0 cm and layer 8, L8~103.8 cm). To further evaluate the DA system, observing system simulation experiments (OSSEs) were designed for Pakistan by assimilating daily 43 44 observations. These idealized experiments produced statistical results that had higher 45 correlation coefficients, reduced root mean square errors, and lower biases for assimilation, which showed that the DA system is reliable and improved soil moisture 46 47 estimation in Pakistan.

48 **Key words:** PODEn4DVar, CLM4.5, data assimilation, soil moisture, Pakistan

50 1. Introduction

51 Soil moisture is an important land surface variable for climatological, 52 hydrological, ecological, and biological studies and has a central role in land-atmosphere 53 interactions. Koster et al.(2004) investigated that the soil moisture anomalies represent 54 significant impacts on regional precipitation after undertaking elaborately designed 55 numerical experiments. The land receives about 65 percent of the precipitation derived 56 from evaporation over land, which is strongly linked to soil moisture (Chahine, 1992).

57 Accurate and precise information of soil moisture at both the spatial and temporal 58 scales is vitally important when attempting to improve weather forecasts, climatic studies and for drought monitoring (Dai et al., 2004). However, the low number of soil moisture 59 60 field measurements over land is a big barrier in acquiring the soil moisture knowledge on 61 broad scales (Robock et al., 2000; Robinson et al., 2008; Crow et al., 2012; Zreda et al., 62 2012). To improve the soil moisture information, several efforts have been taken place 63 without assimilating soil moisture observational data e.g. the North America Land Data 64 Assimilation System (NLDAS) (Mitchell et al., 2004), the Global Land Data Assimilation System (GLDAS) (http://ldas.gsfc.nasa.gov), the Global Soil Wetness 65 Project (http://grads.iges.org/gswp/) (Dirmeyer et al., 1999) and others (Qian et al., 2006; 66 67 Sheffield and Wood, 2008).

68 Currently, regular and field observations, satellite observations, and hydrological 69 modelling are the main sources used to acquire soil moisture information. Soil moisture 70 information collected through field observations, which are of low temporal frequency 71 and have few spatial points. As this information is on point based and therefore cannot 72 showed the soil moisture spatial variations. These field and regular based soil moisture

73 have a great influence on the plants development, chemical activities of fertilizers and the 74 generation of runoff and erosion. Therefore, it has significant impacts on agricultural and 75 the environmental systems. The hydrological modelling is the other important source and the soil moisture simulations generated by hydrological models have good temporal 76 77 frequency and spatial distributions. Though, the precision and accuracy of simulations is 78 strongly linked to input data and model structure. Land data assimilation can provides the 79 reasonable solution to all these issues. It is a technical method that incorporates the 80 physical process data produced by the land surface models (Houser et al., 1998).

81 Recently, there has been progress on assimilation techniques, algorithm, and their 82 applications for many fields like as land, marine, and atmospheric studies (Tian et al., 2011; Zhang et al., 2012). Tian et al. (2011) proposed a hybrid assimilation technique 83 84 known as "Proper orthogonal decomposition (POD)-based ensemble four-dimensional 85 variational assimilation method (PODEn4DVar)". This assimilation algorithm contains 86 the benefits of both variational and ensemble techniques and performed better than both 87 4DVar and the EnKF methods under perfect and imperfect model cases. The computational cost is less when compared to the EnKF and therefore it can be reliably 88 89 integrated into land data assimilation studies.

90 Land models play a fundamental role in land data assimilation systems. The 91 Community Land Model (CLM) (Oleson et al., 2004; Olsen et al., 2010), which is the 92 land module of the Community Earth System Model (CESM) (Hurrell et al., 2013). Even 93 with the scientific improvements in CLM, some studies have shown that when simulating 94 the hydrological state variables, CLM4.0 is biased towards estimating soil moisture at the 95 global and regional scales (Long et al., 2013; Cai et al., 2014). In another study, CLM4.5

96 is used to assimilate AMSR E soil moisture data and overestimation has been observed 97 in soil moisture simulation at most part of the study area (Liu and Mishra, 2017). The 98 earlier versions of CLM have been used in land DA studies for the improvement of soil moisture estimation. For example, CLM2.0 has been used as forecast operator in many 99 100 land DA studies to improve estimation of soil moisture by assimilating *in-situ* soil 101 moisture data (De Lannoy et al., 2007; Tian et al., 2008a; Zhang et al., 2012), and 102 (Kumar et al., 2009) used synthetic observations. Shi et al. (2011) incorporated CLM3.0 103 as a forecast model in the DA framework and assimilated satellite data for the simulation 104 of soil moisture. In another study, Sun et al. (2015) employed CLM3.5 to assimilate the 105 GRACE data using the PODEn4DVar assimilation technique.

106 The aim of this study was to build an assimilation system using CLM4.5 with the 107 PODEn4DVar algorithm to generate the improved and more accurate soil moisture estimation for Pakistan region as a case. Pakistan is now ranked among the top few in the 108 109 list of environmentally vulnerable countries, and faces considerable human challenges 110 because soil moisture changes have implications for health, agriculture, ecology, and water resources under climate change. In such a crucial scenario, reliable and more 111 accurate information on atmospheric and hydrological parameters is needed so that more 112 113 comprehensive research on weather and climate prediction, and hydrological and 114 agricultural studies for the region can be undertaken. In this study, a new DA system was 115 used to obtain preliminary analysis and evaluation results for farmlands across Pakistan 116 through the assimilation of in-situ soil moisture observations. The evaluation experiments 117 were conducted at four agricultural sites, which were representative of various agro-118 climatic zones in Pakistan. This meant that the DA system has been verified under

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119 different hydrological conditions. The second goal of this study was to see the effects on

120 deeper soil moisture prediction when soil moisture was assimilated into the upper soil

121 layers, were also investigated.

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- 123

124 **2. Land data assimilation system for Pakistan**

- Land data assimilation system consists of forecast model, assimilation algorithm and observation operator. In current study, PODEn4DVar was selected as assimilation algorithm whereas CLM4.5 was used as forecasting model.
- 128 2.1 Land Surface Model CLM4.5

The CLM4.5, a global land surface model developed by the National Center for Atmospheric Research United states of America (NCAR).It is attached with the Community Earth System Model version 1.2 (CESM1.2) as a land module. It contains several modifications over previous versions such as improved parameterizations to reduce biases in soil carbon, revised photosynthesis, and canopy radiation schemes (Oleson et al., 2013).

- In CLM4.5, land surface follows the subgrid hierarchy in which each grid cell consist of land units, columns, and plant functional types (PFTs). Grid cells may contain different numbers of land units, e.g. lake, glacier, vegetated and urban. The vegetated land units contain several columns, and each column has 15 layers for soil and five layers for snow, depending upon the snow depth. The soil moisture is calculated within top 10 hydrologically activated layers.
- 141 The volumetric soil moisture content is calculated by the following equation

142
$$\frac{\partial \theta}{\partial t} = -\frac{\partial q}{\partial z} - E - R_{fm}$$
(1)

143 Where θ volumetric soil moisture content in soil column, E is evaporation rate, q is 144vertical soil water flux, R_{fm} is melting or freezing point and z is vertical distance from surface. 2.2 POD-based ensemble four-dimensional variational assimilation method 145 146 Tian et al. (2008b) suggested a hybrid assimilation method using ensemble and 147Proper Orthogonal Decomposition (POD) techniques in which the adjoint model is not 148 needed. Tian et al. (2011) used this technique to develop the PODEn4DVar method, 149 which combined the benefits of the both ensemble and variational approaches. In this method, the analysis field can be obtained by minimizing the following cost function: 150 $J(x') = \frac{1}{2}(x')^{T}B^{-1}(x') + \frac{1}{2}[y'(x') - y'_{obs}]^{T}R^{-1}[y'(x') - y'_{obs}].$ 151 (2)152Where **B** and **R** represent the background and observation error covariance matrices, the superscript T indicates the transpose of matrix, and $x' = x - x_b$ shows the perturbation 153of the background vector $\mathbf{x}_{\mathbf{b}}$ at t_0 . 154 $y'_{obs} = \begin{bmatrix} y'_{obs,1} \\ y'_{obs,2} \\ \vdots \\ \vdots \end{bmatrix}$ 155(3)

156 and
157
$$y' = y'(x') = \begin{bmatrix} y'_1(x') \\ y'_2(x') \\ \vdots \\ \vdots \\ y'_s(x') \end{bmatrix} = \begin{bmatrix} (y_1)' \\ (y_2)' \\ \vdots \\ \vdots \\ (y_s)' \end{bmatrix}$$

(4)

(5)

(6)

158 where y'_{obs} indicates the observation increment and y'represents the simulation of the

159 observation increments by the forecasting model M and observation operator H.

160
$$(y_k)' = y_k(x_b + x') - y_k(x_b).$$

161 $y'_{obs,k} = y_{obs,k} - y_k(x_b).$

162
$$y_k = H_k \big[M_{t_0 \to t_k}(x) \big].$$

163 The model perturbation (*MP*) matrix is then defined as $X' = (x'_1, x'_2, ..., x'_N)$ and the 164 observation perturbation (*OP*) matrix is $Y' = (y'_1, y'_2, ..., y'_N)$. The POD transformation is 165 applied to the *OP* matrix, and which ensure the orthogonality of the transformed *OP* 166 samples ϕ_y . Orthogonal *MP* samples ϕ_x are also obtained by applying the same POD 167 transformation to *MP* matrix. The optimal solution x' is calculated by using weighted 168 mean of *MP* samples.

169
$$x'_a = \phi_{x,r}\beta.$$
 (8)

171 Where $\beta = (\beta_1, \beta_2, \beta_2, \beta_r)^T$. Its corresponding optimal OPs are determined by

172
$$y'_{a} = L(x'_{a}) = L(\phi_{x,r}\beta) = L(\phi_{x,r})\beta \approx L_{x_{b}}(\phi_{x,r})\beta = \phi_{y,r}\beta$$
(9)

173 The control variable of cost function transferred to β after substituting x'_a and y'_a into the 174 cost function.

175 The background error covariance matrix **B** is obtained as in the ensemble Kalman filter 176 (EnKF) (Evensen, 2004):

177
$$B = \frac{\phi_{x,r}\phi_{x,r}^T}{r-1}$$
(10)

(11)

(12)

- 178 Equations (8) and (10) then be substituted into equation (2). By solving the optimal
- 179 problem, the incremental analysis can be attained.

180
$$\phi_{y,r} = \left[(r-1)I_{r \times r} + \phi_{y,r}^T R^{-1} \phi_{y,r} \right]^{-1} \phi_{y,r}^T R^{-1}$$

181
$$x'_a = \phi_{x,r} \phi_{y,r} y'_{obs}$$

182 The final analysis x_a is expressed as follow

183
$$x_a = x_b + x'_a = x' + \phi_{x,r} \phi_{y,r} y'_{obs}$$

184

185 2.3 Soil moisture data assimilation system for Pakistan

The soil moisture data assimilation system for Pakistan consists of the land surface model CLM4.5, the assimilation algorithm PODEn4DVar, and the observation operator. The observation operator (*H*) is needed to create a relationship between observations and the forecast model CLM4.5 simulated state variables. In this study, the observation operator is simply a real matrix, which is used to link simulated soil moisture to observed soil moisture. The observation operator is expressed as

193
$$H = \frac{\sum_{i=1}^{n} w_i y_i}{\sum_{i=1}^{n} w_i}$$
(14)

Where n indicates the dimension of model state vector, w_i is (the weight calculated from the distance between two points (x, x_i) , y_i is the function value at point x_i .

196 This data assimilation system consists of two steps: (1) forecasting and (2) 197 updating of state variable soil moisture. First, the daily simulated hydrogeological 198 variables are obtained by running the CLM4.5 in the current assimilation window and 199 then the updating procedure for the state variables according to PODEn4DVar 200 assimilation method. The updating process for state variables includes the following steps

201 (Fig. 1):

- (a) Read the CLM4.5 daily simulation outputs and historical simulation results to
 obtain sample matrix and then construct the background field vector.
- 204 (b) Construct the model perturbations (**MP**) and observation perturbations (**OP**) 205 matrices.
- 206 (c) Generate **OP** samples ϕ_y and **MP** samples ϕ_x by applying the POD 207 transformation to the **OP** matrix and **MP** matrix respectively.
- 208 (d) Calculate the optimal assimilation increment x'_a and the analysis field x_a as 209 described in the assimilation method.
- (e) Update the initialization file of CLM4.5 using the analysis field x_a and use this
- 211 updated initialization file to run CLM4.5 to get a forecast for the next assimilation
- 212 window and repeat the same steps for updating the state variables.

All 8

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Fig. 1. Flow chart of data assimilation system.

216

217 **3. Evaluation Experiments**

218 3.1 Data description

219 In this study, we used atmospheric forcing data to run land model CLM4.5 and in-220 situ soil moisture information for the preliminary analysis and evaluation of the DA 221 system for Pakistan. CRUNCEP version 4, with spatial resolution of 0.5 °×0.5 °, is a 110-222 year (1900–2010) dataset, which is the standard atmospheric forcing data provided with 223 CLM4.5 and is used to derive model in offline mode. This dataset is generated by 224 combining two datasets: (1) the 6-hourly NCEP reanalysis data with resolution of 2.5° 225 (1948-2010) and (2) the monthly CRU TS3.2 data with 0.5 resolution (1901-2002) 226 (Mitchell and Jones, 2005) (More details on the CRUNCEP dataset are accessible at

http://www.cesm.ucar.edu/models/cesm1.2/clm/clm_forcingdata_esg.html). This dataset has been used widely to derive CLM in studies on plant and vegetation development, and evapotranspiration (Mao et al., 2012; Mao et al., 2013; Shi et al., 2013), and in the TRENDY project (Piao et al., 2012).

231 Pakistan Meteorological Department (PMD) provided the soil moisture 232 observational data for this study. The available soil moisture data from PMD was relative soil moisture and collected three times in a month i.e. 7th, 17th, and 27th, 233 from the 234 meteorological stations situated in agricultural fields across Pakistan. The collected 235 relative soil moisture contents were then changed to volumetric water contents (multiply 236 relative soil moisture contents to soil bulk density and divide it by water density) and used for assimilation and DA system evaluation. 237

238 The four selected agro-meteorological data sites were considered to be representative of different agro-climatic zones in Pakistan. They ranged from arid to 239 240 humid (Chaudhry and Rasul, 2004). The localities of these data sites are presented in Fig. 241 2. Rawalpindi (RWP) agro-meteorological station is situated at the northern side of the 242 Potohar Plateau. It represents rain fed plains with a sub-humid agro-climate. The major 243 crops grown in this region are wheat, groundnut, and fodder. The Faisalabad (FSD) site 244 represents the irrigated plains of central and southern Punjab and is in the dry semi-arid 245agro-climatic zone. Due to well managed canal system, it is a highly productive zone 246where wheat, rice, sugarcane, and cotton are the major crops. Quetta (QTA) is a high 247elevation agricultural rain fed site and has arid climatic characteristics. Wheat is the 248 major crop in this zone. Aridity and low rainfall are the major causes of crop failure in 249 this climatic-zone. Tandojam (TND) represents irrigated arid agro-climatic plains. It has

a well-organized irrigation system, and wheat, cotton, and rice are the major crops in this





253

Fig. 2. Location map of the study sites in Pakistan.

254

255 3.2 Experimental design

256 3.1.1 In-situ soil moisture assimilation

The assimilation experiments were conducted at the four available soil moisture sites in Pakistan to evaluate the performance of the DA system based on CLM4.5 and PODEn4DVar. For reasonable initial conditions, a 100-year simulation of CLM4.5 was run at every data site using CRUNCEP atmospheric forcing data. The outputs of the spin-up simulation were choose as the initial conditions for all types of assimilation experiments. The spatial resolution of the model was set to be 0.1×0.1 for all in-situ soil moisture data assimilation experiments. In all assimilation experiments, the historical 264 sampling scheme (Wang et al., 2010) was used and ensemble size was fixed to be 50

265 members. Another 50-year simulation of CLM4.5 was run using the spin-up results from jor

266 the 100-year simulations as initial conditions.

267

268

Table 1. Assimilating soil depths and the corresponding CLM4.5 layers

In-situ soil depth (cm)	CLM4.5 layers (depth cm)
5	L3 (~6.2)
10	L4 (~11.9)
20	L5 (~21.2)
30	L6 (~36.6)

270

269

271 In current study, the in-situ soil moisture information from four soil-depths (0–5 272 cm, 5-10 cm, 10-20 cm, and 20-30 cm) for year 2006 were assimilated and the 273 corresponding layers of CLM4.5 for these soil-depths are described in Table 1. To check 274 the performance of the DA system, alternative soil moisture observations were 275 assimilated and non-assimilated observations were considered to assess the DA system.

276 The effects of assimilating soil moisture observations at these four upper soil-277 depths on deeper soil-depths moisture simulations (30–40 cm, 40–50, 50–70, and 70–90 278 cm) by CLM4.5 were also investigated. Table 2 shows the deep soil layers information. It 279 should be noted that both the 40 cm and 50 cm soil-depths exist within a single layer of 280 CLM4.5, but observed soil moisture data was available for these depths. Therefore, this

information was used to evaluate the 40 and 50 cm soil-depths as well as the70 and 90

cm soil-depths.

283

284

 Table 2. Evaluating soil depths and the corresponding layers of CLM4.5

In-situ soil depth (cm)	CLM4.5 layers (depth cm)
40	L7 (~62.0)
50	L7 (~62.0)
70	L8 (~103.8)
90	L8 (~103.8)

s lot

285

286

287 *3.1.2 Observing system simulation experiments (OSSEs)*

288 Observing system simulation experiments (OSSEs) are considered one of the best options for the assessment and evaluation of a DA system because it produces both the 289 290 "observations" and "true" states. In this study, OSSEs were conducted for Pakistan. The 291 100-year spin up simulation of CLM4.5 with 1 degree horizontal resolution was run using 292 CRUNCEP data to acquire the suitable initial conditions for the DA experiments. Daily 293 simulations of CLM4.5 for year 2004 using CRUNCEP atmospheric forcing data were 294 treated as the "true" fields in this experiment. The daily averaged soil moisture values 295 calculated by adding errors to the "true" fields were used as the "observations" for the 296 assimilation. Both the simulation (without DA) and assimilation experiments were driven 297 by QIAN atmospheric forcing data for year 2004. In OSSEs, the ensemble size and

sampling strategy were kept the same as those used in the in-situ soil moisture assimilation experiments. In these experiments, assimilation was carried out for all ten layers of the land model whereas for in-situ soil moisture assimilation experiments, only

301 four CLM4.5 layers were used for assimilation.

302

303 3.3 Results and discussion

304 3.3.1 In-situ soil moisture assimilation results

 \mathbf{C}

305 *3.3.1.1* Assimilation and evaluation results for the top layers

The preliminary results of the DA system for the top layers assimilation are described in Fig. 3. The black dots in Fig. 3 indicate the observations used for the evaluation, whereas the green dots are the assimilated observations. Figure 3 (a, b, c, d) shows the assimilation results for the 0–5 cm soil layer whereas Fig. 3 (e, f, g, h) for the 20–30 cm soil layer at the experimental sites. The assimilation results for soil-depths 5–



311 10 and 10-20 cm are not shown because they produced similar results.

alternative soil moisture observations are assimilated and remaining observations are used for the evaluation of DA system. It is observed that the assimilation time series for all stations at both soil depths (5cm and 30cm) is much closer to black dots which are the soil moisture observations used for evaluation than the simulation. The closeness of assimilation line to black dots clearly shows that the assimilation improved the estimation of soil moisture.

325 The statistical indices for all the sites clearly showed that assimilation has 326 significant improvement in soil moisture estimation with higher correlation coefficients, 327 smaller RMSE, and lower BIAS (Fig. 4). The FSD and RWP sites at two soil layers (0-5 328 cm and 5-10 cm) with negative BIAS (Fig. 4 (i, k)) showing the underestimation whereas 329 the other two stations (Fig. 4(j, l)) overestimated the soil moisture estimation with respect 330 to observations. Overall the simulations showed the overestimation in soil moisture with 331 higher biases at all stations and at maximum number of soil-depths than the assimilation 332 run (Fig. 4(i, j, k, l)). This overestimation in soil moisture for simulation run is consistent 333 with the previous studies (Long et al., 2013; Cai et al., 2014). However, this 334 overestimation of soil moisture was reduced by DA, which decreased the RMSE (Fig. 4(e, 335 f, g, h)) and produced higher correlation coefficients (Fig. 4(a, b, c, d)). At the QTA site, 336 which was a rain fed and high elevation agricultural field site, soil moisture data was only 337 collected during the wheat season because wheat was the major crop. The soil moisture 338 data for two wheat seasons for year 2006 and 2007 were used for the assimilation (Fig. 339 3(d, h)).

Thus the statistical analysis indicated that soil moisture estimation improved (Fig.4) when the in-situ soil moisture data was assimilated at four top soil layers (0–5 cm,

342 5-10 cm, 10-20 cm, and 20-30 cm) and hence the performance of DA system was

343 reasonable.

344

345 346

347



Fig. 4. Statistical analysis (R, RMSE, and BIAS) of simulated (without DA) and assimilated soil moisture against in-situ observations for different soil layers at different sites in Pakistan.

349

350

351

352 *3.3.1.2 Effects of assimilation on the deep layers*

Another aim of this research was to explore the effects of the top soil layers soil moisture assimilation over the deeper soil layers soil moisture estimates. The evaluating soil layers information is shown in Table 2. Figure 5 shows the assimilation effects at soil- depths 40–50 and 50–70 cm, respectively, for all the experimental sites. The results for soil-depths 30–40 and 70–90 cm are not shown because of similar results. Soil moisture observations for QTA were not available for soil layer 70–90 cm, and therefore, the results at QTA 90CM are missing for evaluation.

360 Figure 5 shows that the assimilation time series is closer to the observations than 361 the simulation (without DA), which suggests that soil moisture estimations for the deeper 362 soil layers have improved, even when there is no assimilation of soil moisture done in these soil layers of model. Figure 4 also represents the statistical indices for the deeper 363 364 soil layers (30-40, 40-50, 50-70, and 70-90 cm). It is observed that simulation had a 365 lower correlation coefficient and higher RMSE as compared to assimilation for all the deeper soil layers at all the experimental sites which shows that assimilation has 366 367 improvement in soil moisture estimation at deeper soil layers (Fig. 4(a, b, c, d)). Higher 368 biases for simulation were also recorded for the deeper soil layers than the top soil layers, 369 except for RWP where the biases difference was smaller at the deeper soil layers than the 370 other sites (Fig. 4(i, j, k, l)). These higher biases might be due to systematic biases of 371 CLM (Long et al., 2013; Cai et al., 2014). Overall the statistical analysis with higher 372 correlation coefficient, less RMSE and BIAS showing that the assimilation in the top soil



that the DA system can be reliably used for soil moisture assimilation.



377 Fig. 5. Effects of assimilation on two soil layers (40-50 cm and 50-70 cm) at different 378 sites (red line: simulated soil moisture (without DA), blue line: assimilation, and black 379 dot: observed soil moisture). 101

- 380
- 381

382 3.3.1.3 Soil temperature and surface heat fluxes

383 Figure 6 shows the differences in soil temperature between the simulated (without 384 DA) and assimilated values produced by CLM4.5 for the top four soil layers. The 385 difference is obtained from the simulated minus assimilated values for daily soil 386 temperature. However, the difference was only calculated for the assimilation days at the four experimental sites. The magnitude of the soil temperature difference varies from site 387 388 to site and layer to layer. The maximum temperature difference (14 K) was observed at 389 QTA whereas the minimum difference was 0.9 K at the FSD station. These variations in 390 soil temperature were substantial, which indicated that assimilation of soil moisture 391 observations in CLM4.5 produced different results for soil temperature as well.



Fig. 6. Differences between simulated (without DA) and assimilated daily soil

temperatures in the top four soil layers of CLM4.5 at four different experimental sites.

395

396 The soil moisture difference can change the simulation of surface latent flux, 397 whereas the sensible heat flux may show adverse performance because of the change in 398 soil temperature (Tian et al., 2008a). Figure 7 shows the simulated minus assimilated 399 differences in latent heat and sensible heat fluxes at the different sites. The latent heat flux difference varies from -21.5 to 152.5 W/m² among the experimental stations, 400 whereas -0.04 to 115.5 W/m² for the sensible heat flux difference. These higher 401 differences in surface heat fluxes could produce striking impacts on the land-atmosphere 402 403 interaction at all the stations.



405Fig. 7. Differences between simulated (without DA) and assimilated daily surface latent406and sensible heat fluxes at four experimental sites.

408

409

410 *3.3.2 Observing system simulation experiments (OSSEs)*

411 Figure 8 shows the results of OSSEs experiment, carried out for Pakistan. In these 412 experiments, daily soil moisture observations were assimilated only for the rainy season, 413 which is from June-August (JJA) in Pakistan to evaluate the DA system. The constant error of 0.012 was added to the "true" fields to generate the daily soil moisture 414415 observations and these artificial observations were assimilated into the system. Figure 8 416 shows the evaluation results of daily assimilation for only four soil layers whereas 417 assimilation was carried out for all the soil layers of CLM. The results for the other soil layers are not shown. Daily assimilation produced significantly good performance during 418

419 the rainy season (JJA).

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- 421



423	Fig. 8. Time series for the soil moisture observations, true fields, assimilation and
424	simulation (without DA) for the 1 st , 3 rd , 6 th , and 8 th soil layers of CLM4.5 for Pakistan.
425	\sim
426	
427	
428	From the Fig. 8, it is cleared that the assimilation time series is more consistent
429	and closer to observation and "true" time series than the simulation for the whole time
430	period of experiment, which clearly indicates that there is an improvement in soil
431	moisture estimation. Table 3 shows the statistical analysis for the daily OSSEs
432	experiments. The results with higher correlation coefficient and lower RMSE values for
433	assimilation suggest that the DA system has improved the estimation of daily soil
434	moisture. The simulation overestimates soil moisture, which is similar to previous results
435	(Long et al., 2013; Cai et al., 2014), and this overestimation is reduced in all soil layers
436	by assimilation. Overall, the OSSEs results showed that the data assimilation system can
437	reliably estimate soil moisture in Pakistan.
438	

439 Table 3.Comparison of the root mean square errors (RMSE) and the correlation
440 coefficients (R) for assimilation and simulation (without DA) in OSSE experiments
441

	1 st layer	3 rd layer	6 th layer	8 th layer
RMSE (sim)	0.30	0.21	0.49	0.23
RMSE (ass)	0.075	.046	.035	0.030
R (sim)	0.70	0.72	0.80	0.74
R (ass)	0.98	0.97	0.96	0.94

443 **4. Conclusions**

444 In current study, a general framework for soil moisture data assimilation (DA) has 445 been developed for Pakistan. In this soil moisture DA system, PODEn4DVar was used as 446 the assimilation algorithm whereas the Community Land Model CLM4.5 was selected as the forecasting operator. For the performance evaluation of the DA system, preliminary 447 analysis and evaluation experiments were conducted at four agricultural sites from 448 449 different agro-climatic zones across Pakistan, and the in-situ information of soil moisture 450 were assimilated. The alternative soil moisture observations for four top soil-depths i.e., 0-5 cm, 5-10 cm, 10-20 cm, and 20-30 cm were assimilated in CLM4.5 for evaluation. 451 452 The correlation coefficients, root mean square errors, and the biases after assimilation significantly improved for the top four soil layers. The results indicated that the DA 453 454 system can produce more accurate and precise soil moisture estimations.

The effects of top layers soil moisture assimilation over lower soil-depths, i.e., 455 456 30–40 cm, 40–50 cm, 50–7 0cm, and 70–90 cm, were also investigated. The statistical 457 indices (R, RMSE, and BIAS) improved at all sites and for all soil-depths. These results 458 are a clear indication that assimilation in the top soil layers can also improve CLM4.5 soil 459 moisture estimations in deeper soil layers. Thus, the evaluation results showed that DA 460 system based on PODEn4DVar and CLM4.5 can improve soil moisture simulation. For 461 further assessment of the soil moisture DA system, we conducted OSSEs experiments for 462 Pakistan. However, these experiments were only undertaken in, only the rainy season 463(JJA). To validate the performance of the DA system, daily soil moisture information 464 were used for assimilation. The evaluation results from the OSSEs experiments clearly 465 showed that assimilation can improve soil moisture estimation.



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